Application of Particle Swarm Optimization Algorithm in Talent Policy System Optimization

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Abstract. As a macro-management system, the complexity of the talent policy system is reflected on that the evaluation results of policy factors are hard to quantify, and the mismatching between the system optimization direction and the social and psychological requirements of talents, et al. In order to solve above problems, a Shaanxi province talents policy system is used as example, a questionnaire about policy satisfaction, engagement and demission tendency is designed and the questionnaire data are collected by using empirical survey method. Based on the questionnaire data, the chaotic particle swarm optimization (CPSO) algorithm is used to build the relationship model for talent policy system, i.e. the mathematical model of the talent policy system. By analyzing the gain coefficient of the model, the contribution rate of different talents policy for the policy satisfaction, engagement and the demission tendency can be obtained. The simulation results show that, compared with the traditional regression approach to build the mathematical model of the talent policy system, the CPSO method has high accuracy, low complexity for computer realization and can be extended to the optimization of other policy systems.

1 Introduction

The flow rules of the talents inside or outside the country show that, good institutional mechanisms have more conducive to the growth and function exertive of the talents [1]. Therefore, how to adapt the trends of industrial structure optimization and upgrade, and continual enhance the attraction of talents, are the reality and urgent project. The modeling and controlling of the talents policy system became very important research issues.

2 Building of the Relationship Model for the Talent Policy System

In this paper, a Shaanxi province talents policy system is used as example, a questionnaire is designed, that the effects of different policy factors to the talent satisfaction, engagement and demission tendency are collected. From the questionnaire data, the relationship model between the different policy factors and the talents policy satisfaction can be expressed as

 $S = X_1 * P_1 + X_2 * P_2 + X_3 * P_3 + X_4 * P_4 + X_5 * P_5 + X_6 * P_6 + X_7 * P_7 + X_8 * P_8 + X_9 * P_9 + X_{10} * P_{10}$ (1)

where S denotes the mean value of talents policy satisfaction, X_i (i=1, ..., 10) represent the satisfaction gain coefficient of the different policy factors, X_i is bigger means that the corresponding policy factor has larger contribution for the talent policy satisfaction, otherwise the contribution is smaller. P_1 to P_{10} represent satisfaction of different policy factors, shown in Table 1:

7	Variable	Policy Factor		Variable	Policy Factor
	P_1	enterprise	management	P_6	culture policy
	P_2	living environment		P_7	social atmosphere and respected
	P_3	talent evaluation		P_8	introduction policy
	P_4	incentives policy		P_9	talent market service

Table 1 P_{10} represent satisfaction of different policy factors

It is obvious, the key problem of the talents policy satisfaction relationship model building process, is calculate the gain coefficient X_i according the questionnaire data.

 P_{10}

policy awareness

The traditional regression approach, but the regression model data needs to meet the effect accumulation, without variable measurement error and other multiple assumptions, and that the test process is complicated [2], so we use a nevol CPSO method [3,4] to product the multi-objective gain X_i in Eq.(1), thus the relationship model of the talents policy satisfaction system is built and the improved policy recommendations are proposed, this is the main motivation of the paper.

2.1 CPSO method for Talents Policy System Optimization

regional flow policy

 P_5

In the traditional Particle Swarm Optimization (PSO) method[5], the distribution of the initial particle has significant effect on performance of the optimizing algorithm, the uneven distribution initial particles may lead the algorithm instability, CPSO method, can initialize particles to even distribution by using the chaos map function. In this paper, an improved CPSO method[3] is used for talents policy system optimization, the improved CPSO method, itproposed to initialize the initial particles by using the unilateral coupled lattice spatiotemporal chaotic map, the chaotic map is expressed as

$$L_n(m+1) = (1-\varepsilon_n)f[L_n(m)] + \varepsilon_n f[L_{n-1}(m)]n=1, 2, 3, ...$$
 (2)

where f $[L_n(m)]$ is chaotic map, $f[L_n(m)] = \mu L_n(m)(1 - L_n(m))$, $L_n(m)$ denotes the particle, n is the dimension of particle (space), m represents the population length of particle (discrete-time), ε_n is the coupling strength. In Eq. (2), the initial particles are directly produce, which not only satisfy the chaos distribution in space (dimension), but also satisfy the chaos distribution in discrete-time, the unilateral coupled lattice spatiotemporal chaotic map is more sensitive to the initial value, and with more stringent boundary conditions, thus has better performance. The unilateral coupled lattice spatiotemporal chaotic map diagram shown in Fig.1:

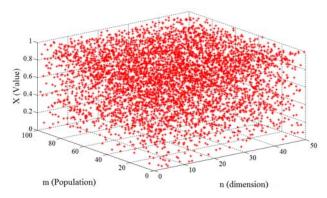


Fig.1. The state diagram of unilateral coupled lattice spatiotemporal chaotic time space

The traditional CPSO methods use logistic map, Figure 3 shows the distribution comparison results between the traditional logistics map and the unilateral coupled lattice spatiotemporal chaotic map. Figure 3(a) and (b) are the box-plot curve of the proposed method and the logistic map respectively. Figure 3(c) is the comparison results of N-dimension elements between the proposed chaotic map and the traditional logistic map when m=30. From Fig.3, we know that, the multi-dimensional particles, generated by the proposed chaotic map, are uniformly distributed in the searching space, and compared with the traditional logistic map, the proposed method are more evenly distributed in N-dimension space from the box-plot curve. From Fig.3(c), we can see that, compared to the traditional logistic map, the proposed method has tighter boundary conditions in the sense of no boundary point as appear in "red star points" in the left subplot of Fig.2(c) (by using the logistic map)

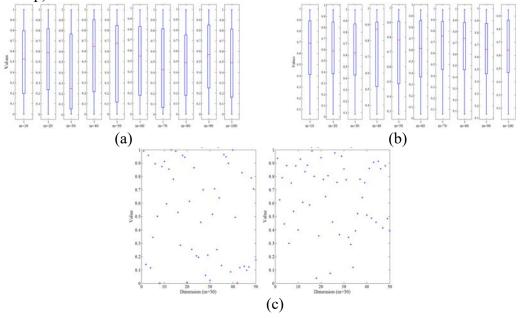


Fig.2. Comparison of different chaotic map (a) the proposed chaotic map;(b) logistic maps;(c) N-dimensional element distribution comparison when m=30.

Using the novel CPSO method, the relationship model of the talents policy satisfaction system can be obtained. The gain coefficient X_i are treat as the particles, from Eq. (1), there are 10 gain coefficients, thus the dimension N of particle is 10. In the k-th iteration, the particle value X_m is obtained, and the cost function, which presents the error between the actual mean talent satisfaction value collect by questionnaire and the estimated value calculate by Eq. (1), is calculated. Using the following equation, the velocity and position of n-dimensional (n = 1,...,N) particles m can be updated.

$$V_m(n, k+1) = V_m(n, k) + c1 * r1 * (Y_m(n, k) - X_m(n, k)) + c2 * r2 * (Y_g(n, k) - X_m(n, k))$$
(3)

$$X_m(n, k+1) = X_m(n, k) + V_m(n, k+1)$$
(4)

where V_m denotes the speed of particle, Y_m denotes the individual extreme value, Y_g denotes the global extreme value, c1,c2 is learning factor, non-negative constant, r1,r2 is the two independent random numbers between [0,1]. The detailed optimization process is showing blow:

Step1, determine the parameters to be optimized is the coefficient X_i (i=1, ..., 10) in formula (1), the values of X_i are the N-dimensional particle positions, N=10, initialized the population size of particles is M=10000. The maximum number of iterations is k_{max} = 50. Using Eq. (2) unilateral coupled lattice spatiotemporal chaotic map to initialize N-dimensional particle position X_m (:, 0) = $[X_m(1,0), ..., X_m(10,0)] \in [0,1]$, m = 1, ..., M; Similarly initialize the global particle best position $Y_g(0) = [Y_g(1,0), ..., Y_g(10,0)] \in [0,1]$.

Step2, start the process of iteration by running algorithm optimization program, the coefficients $(X_m \ (1, k) = X_1, ..., X_m \ (10, k) = X_{10})$ represents the current k iteration particle m position, take $X_m \ (1,k)$ into Eq. (1), where $k=1, ..., k_{max}$. The calculation results of particle m corresponding to different coefficients in k iteration expressed as:

$$S_g(m)=X_m(1, k)*P_1+X_m(2, k)*P_2+X_m(3, k)*P_3+X_m(4, k)*P_4+X_m(5, k)*P_5+X_m(6, k)*P_6+X_m(7, k)*P_7+X_m(8, k)*P_8+X_m(9, k)*P_9+X_m(10, k)*P_{10}.$$

Thus, the objective function $J(m, k) = 1 / (S-S_g(m))$ can be calculated, where S is the mean value of the talents policy satisfaction collect from actual questionnaire, P_I to P_{I0} is talent policy factors average value also collect from actual questionnaire.

Step3, for each particle m in k iteration, (m= 1, ..., M), compare the objective function value of current particle with the objective function value of individual extreme particle, if the present objective function value is better than the objective function value of individual extreme particle, the current particle become the new individual extreme particle. This process is expressed as:

If
$$J(m) \ge J_{max}(m)$$
, then $J_{max}(m) = J(m,k)$, and $Y_m(:,k) = [Y_m(1,k), Y_m(2,k), ..., Y_m(N,k)]$.

Step4, for the k iteration particle m(m=1, ..., M), update particles speed and position according to individual extreme value Y_m and global extreme value Y_g of all the particles. The first iteration (k=1), the global extreme value Y_g (0) using initializing random value in Step1, in each later iteration, the global extreme value is calculated from step 5 in the last iteration.

Step5, comparing all the objective function value of M particles, (saved the particle which the objective function is maximum of M particles as the global extreme value. This process is expressed as: $J_g(m, k) = \max\{J(1, k), ..., J(M, k)\}$; then particle M is the global optimal solution, expressed as $Y_g(:, k) = [Y_g(1, k), Y_g(2, k), Y_g(N, k)] = [X(1, k), X(2, k), ..., X(N, k)]$.

Step6, if reaches the stop condition ($k=k_{max}$), end the program and display the global extreme value Y_g and the corresponding objective function value, otherwise k=k+1 and back to step 1 to continue the iterative process.

2.2 Optimization Results Analysis

From above steps, which is programed by Matlab, the relationship model of policy factors satisfaction and overall satisfation is given as:

$$S=0.030665*P_1+0.082074*P_2+0.26538*P_3+0.12782*P_4+0.002439*P_5+0.14332*P_6+0.16516*P_7+0.13447*P_8+0.035168*P_9+0.1017*P_{10}$$
 (5)

Similarly, we can build other relationship models such as the relationship model of policy factors

satisfaction and demission tendency. Compared with the results, establish traditional regression equation need to extract the coefficient of correlation>0.6. By using SPSS17.0, we got the larger coefficient computing result shown as Table2:

Table 2 the larger coefficient computing result

		P_1	P_2	P_3	P_4	P_5	P_6	P_7	P_8	P_9	P ₁₀	Overall
P_1	Pearson	1	.700*	.716*	.273*	.632*	.943*	25	018	114	192	.594**
	Sig.		.000	.000	.003	.000	.000	.004	.430	.12	.27	.000
	N	102	102	102	102	102	102	102	102	102	102	102
P_3	Pearson	.716*	.375*	1	.275*	.444*	.622*	132	.284*	081	293	.555**
	Sig	.000	.000		.003	.000	.000	.092	.002	.21	.00	.000
	N	102	102	102	102	102	102	102	102	102	102	102

The largest coefficient is 0.594, it does not meet the requirements of the regression model, to avoid error accumulation, the regression model cannot be established.

3 Summary

By using advanced particle swarm optimization algorithm, the establishment of complex talent policy system model can be achieved, which provides basis for analyzing the role of policy and proposing the optimization proposal. The particle swarm optimization algorithm has high accuracy, low complexity for computer realization and can be extended to the optimization of other management systems.

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